

Shape Descriptors, Classifier fusion and other Techniques applied to Graphics Recognition and related problems

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Personal information

- 2001: “Maîtrise” in Mathematics by the Autonomous University of Barcelona (UAB)
- 2003: Master in Computer Vision by the Computer Vision Centre
- 2006: PhD in Computer Science by the UAB and Nancy 2 University (UN2)
- 2007: Visiting Scientist in the CVPR Unit of the Indian Statistical Institute (ISI)
- 2008: ATER at UN2.
- Nowadays: Research fellow at Technological Institute of Computer Science (ITI in Spanish)

Outline

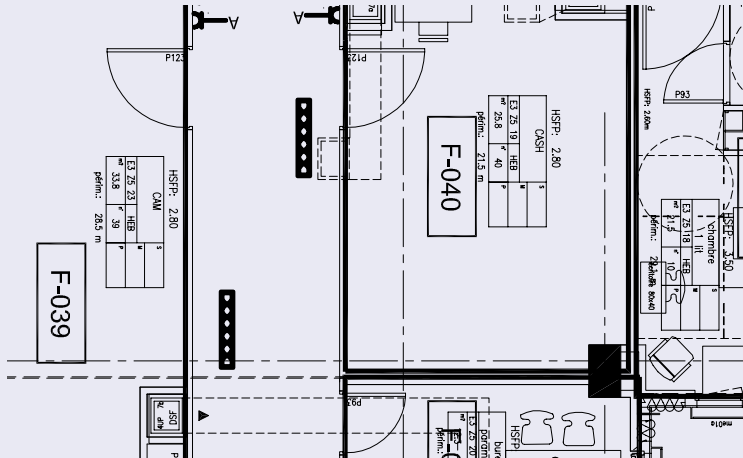
- 1 Motivation
 - Source of problems
 - Tasks of interest
 - Research problems
- 2 Recognition Process
 - Scheme Process
 - Shape Descriptors
 - Classifier Fusion
 - Correlation Filters
- 3 Example of applications
 - Graphics Recognition
 - Script Identification
 - Symbol Spotting
 - Feature Selection
 - Interactive Handwritten Recognition

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Technical Documents

Zoomed...



Personal information

Motivation

Recognition Process

Example of applications

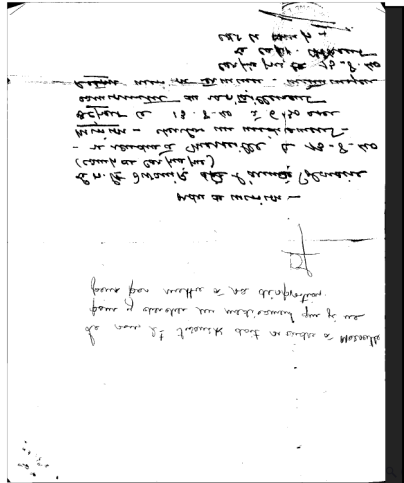
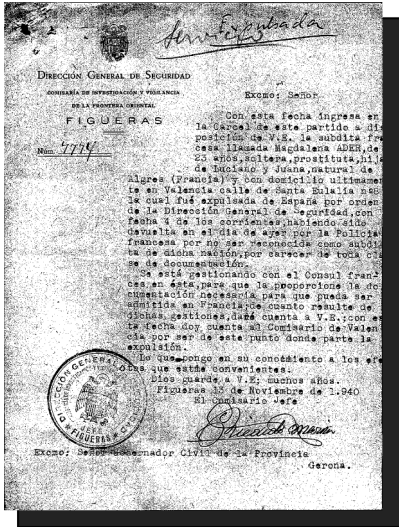
The End

Source of problems

Tasks of interest

Research problems

Historical Documents



Historical Documents

handwritten text...

ordre de mission -
Le sr. Lt Dwanir de l'armée Polonaise
(capitaine Carpié) -
- se rendra à Marseille le 13-8-40
Mission - chercher un médecin -
Départ le 13-8-40 à 6h30 avec
équipement de ravitaillement
Retour mission terminée - même moyen
Carpié par le 13-8-40
Le capit. Dwanir
est le chef +

Tasks of interest

- Extract information from technical and historical documents
- Find graphical information through document collections
- Script identification
- Handwritten recognition

Open questions:

- How represent graphical entities?

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By using descriptors

- How to organise information?

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Applying indexing strategies

- How to determine which are the best descriptors?

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Evaluating descriptors on reference benchmarks

- How to improve performances?

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Evaluating descriptors on reference benchmarks

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Combining multiple classifiers

Methods

- Definition and computation of new descriptors

Methods

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- Indexing and structuring data

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- Definition and computation of new descriptors
- Indexing and structuring data
- Performance evaluation

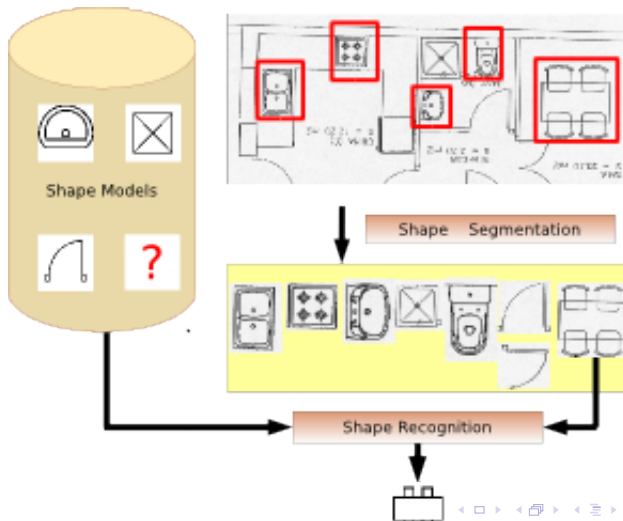
Methods

- Definition and computation of new descriptors
- Indexing and structuring data
- Performance evaluation
- Research on machine learning methods

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Scheme Process



Recognition Process

Denoise

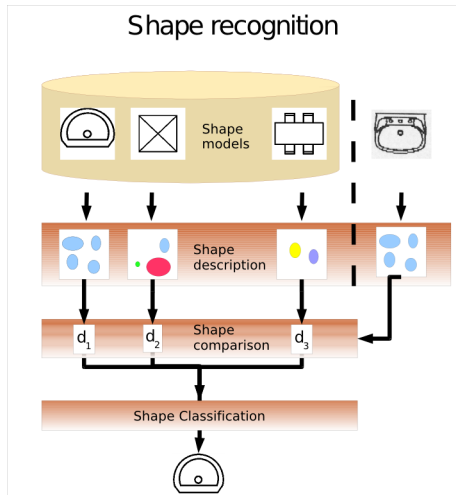
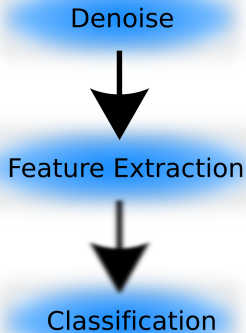


Feature Extraction



Classification

Recognition Process



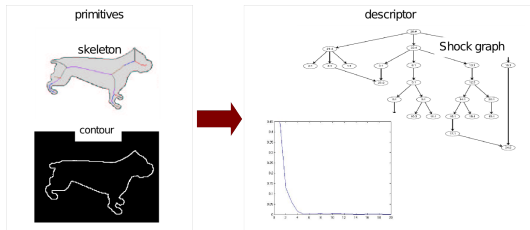
Shape Descriptors

Definitions

A Feature Extraction Method (FEM) is a map: $D : X \rightarrow Y$ such that:

The elements $x \in X$ are primitives.

For any $A \subset X$, $y_A = D(A)$ is a descriptor.



Review of Shape descriptors

Primitives:

- 1D (contour):
 - Fourier.
 - Stochastic: Autoregressive methods.
 - Curvature: Curvature Scale space (CSS).
 - Geometric invariants.
- 2D (region):
 - Polar: Polar Fourier, Fourier-Mellin, Radon/Hough, Zernike moments, Angular Radial transform (ART), **ridgelets**.
 - Moment-based: geometric, Zernike, Legendre.
 - Local norm based: R-Signature, Zoning, **LNR**.

Descriptors:

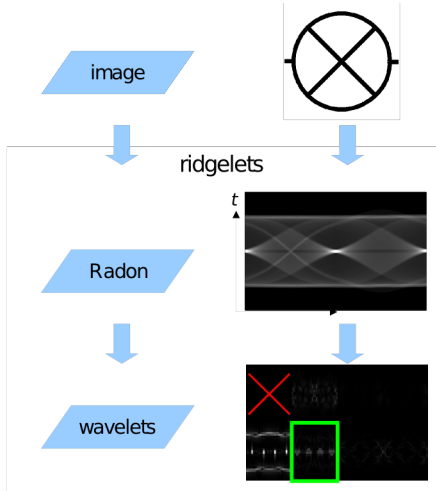
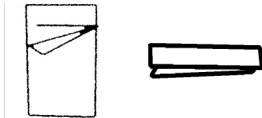
- Multiresolution:
 - Space scale: CSS
 - MRA: wavelets, **ridgelets**.
- Structural:
 - Graph-based.
 - Grammar-based.

Ridgelets transform

Document degradation and vectorial distortion make difficult vectorization process



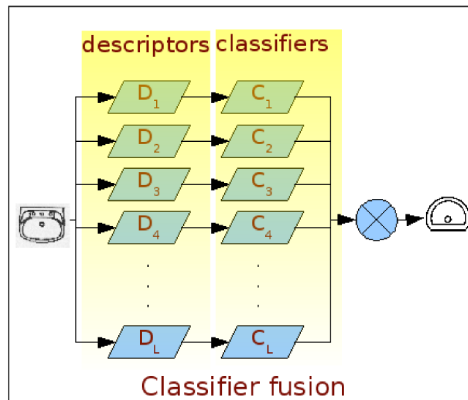
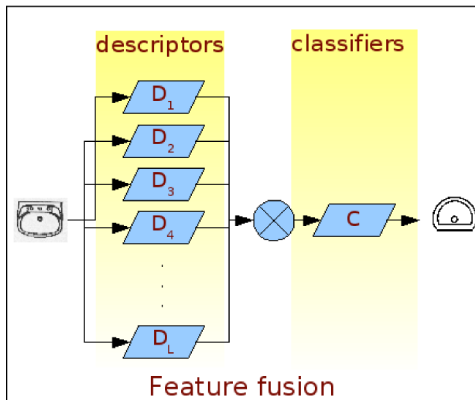
We should look for a different way to detect linear singularities



Definition of ridgelets descriptors: multiresolution, 2D, polar and

Combination Schemes

One descriptor is not usually enough.



Classifier Fusion: review

Given J Classes: $\{\omega_1, \dots, \omega_J\}$ and L classifiers for each class, which is the best way to combine them?

- Bayesian approach: Classifiers return conditional probability: $Pr(X_l|\omega_j)$ [Kitler et al. 1998]

$$Pr(\omega_j|X_1, \dots, X_L) = \frac{Pr(\omega_j) \prod_l Pr(X_l|\omega_j)}{Pr(X_1, \dots, X_L)}$$

which explains some classic combination rules:

$$\frac{1}{L} \prod_l Pr(X_l|\omega_j) \quad \frac{1}{L} \sum_l Pr(X_l|\omega_j) \quad \max_l Pr(X_l|\omega_j)$$

Classifier Fusion: review (contd.)

- Logistic regression. The probability $Pr(\omega_j|X_1, \dots, X_L)$ is fitted by an additive model of the **logit** function:

$$\log \frac{Pr(\omega_j|X_1, \dots, X_L)}{1 - Pr(\omega_j|X_1, \dots, X_L)} = \sum_l \alpha_l Pr(\omega_j|X_l)$$

- Boosting algorithms: Friedman et al. [1998].
- Generalization of the Borda Count method: Ho et al. [1994].

Notation and Simplifications

2 simplifications

- 2 class classifiers: $\{-1, 1\}$
- linear combination: $\sum_I \alpha_I C_I$

Name	Notation	Domain	Meaning
Shape	S	Ω	the shape to recognize
Label	Y	$\{-1, 1\}$	the class of shapes
Descriptor	$X = FEM(S)$	\mathbb{R}^d	the descriptor computed from shapes
Prediction	$Z = C(X)$	\mathbb{R}	the classifier output
Validation	$U = YZ$	\mathbb{R}	the validity of the prediction

Linear Combination of Classifiers

Problem:

With the precedent definitions of r.v. the problem of finding the optimal linear combination rule is expressed as the optimization of the following objective function:

$$\alpha_{optimal} = \arg \min_{\alpha} Pr\left(\sum_I \alpha_I U_I < 0 | S\right)$$

with constraints:

$$\begin{aligned} \alpha_I &> 0 \quad \text{for all } I \\ \sum_I \alpha_I &= 1 \end{aligned}$$

IN and *DN* methods

- Denote $U = (U_1, \dots, U_L)$.
- μ and Σ , respectively, mean and covariance matrix of U (σ_I^2 variance of U_I)
- $A = \sum_I \alpha_I^{\mathcal{N}}$ and $B = \sum_I \alpha_I^{\mathcal{D}}$.

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U_l are conditional
independents

- $\alpha_l^{\mathcal{D}} = \mu_l$ if $\sigma_l \approx 0$.
 - $\alpha_l^{\mathcal{N}} = \frac{\mu_l}{\sigma_l}$, otherwise.
- $$\alpha_{op} = \lambda_{\mathcal{N}} \alpha^{\mathcal{N}} + \lambda_{\mathcal{D}} \alpha^{\mathcal{D}}$$

$$\lambda = \begin{cases} \left(\frac{A-B}{A^2}, \frac{1}{A} \right) & \text{if } A > B \\ \left(0, \frac{1}{B} \right) & \text{if } A \leq B \end{cases}$$

IN and DN methods

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U_l are dependents to each
 other

Minimize the object function:

$$\phi(\alpha) = \left\langle \frac{\alpha}{\alpha^t \Sigma \alpha}, \mu \right\rangle$$

Subject to the constraints:

$$\begin{cases} \alpha_l > 0 & \text{for all } l \\ \sum_l \alpha_l = 1 \end{cases}$$

Correlation Filters

- Collaboration with Prof. Djemel Ziou (univ Sherbrooke, Canada) and S. Tabbone (univ. Nancy 2 - LORIA, France)
- Idea: Apply correlation filters to CBIR problems.
- Related work: Face and Object Identification, **MACE** filters

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Variational approach: Main Idea

K semantic classes: $1, \dots, K$; $v^{i,k}$ image collection, h_k correlation filters.

$$\max \frac{\int_{-w}^w v^{i,k} \circledast h_k}{\int v^{i,k} \circledast h_k}$$

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Example of applications

- Use of shape descriptors and Classifier fusion methods to Graphics (segmented) recognition problems
- Use of low level features and SVM classifiers to Thai-English script identification
- Use of Correlation filters to CBIR problems: symbol spotting.

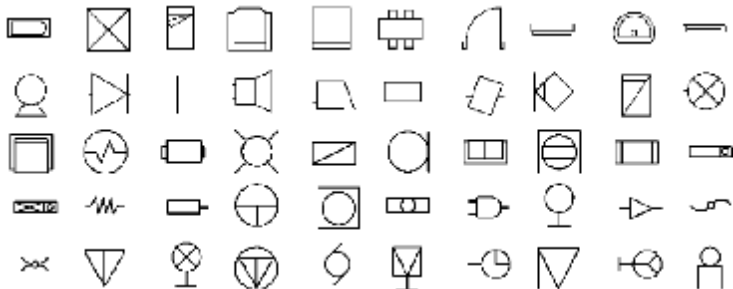
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- Use of Correlation filters to CBIR problems: symbol spotting.
- Use of Genetic algorithms for feature selection
- Shape context and Video Google for symbol spotting

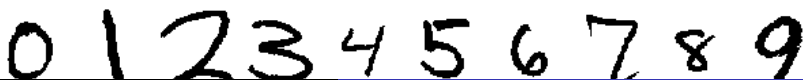
Graphics Recognition

Validation on benchmark datasets:

- Graphics (GREC):



- and digits (MNIST):



Script Identification

- Collaboration with Sukalpa Chanda, PhD candidate, and Umapada Pal (ISI)
- Use of 7 features to train two-class SVM

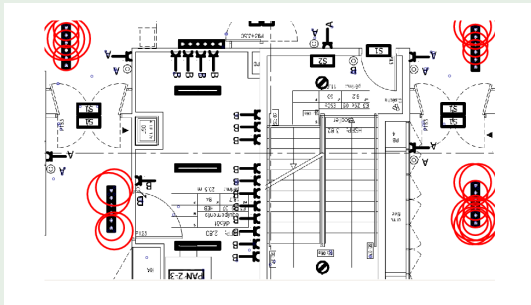
Exemple

และร่วมถวายพระพรเนื่องในวโรกาสพระราชสมภพของสมเด็จพระบรมราชินีนาถ
ใครที่เป็นอเมริกันชาติเช่นมีสิทธิ์ออกเสียงเลือกตั้ง ทางสมาคม
American group ขอเชิญพบปะกับผู้สมัครทุกระดับ ตั้งแต่ระดับสมาชิกสภา

Symbol Spotting

- Thi-Oanh Nguyen, PhD candidate, and S. Tabbone (LORIA)
- SCIP: Shape Context of Interest Points and Video Google.
- Symbol spotting: detect and localise non-segmented symbols

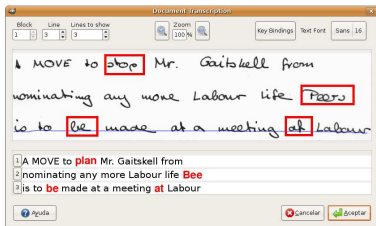
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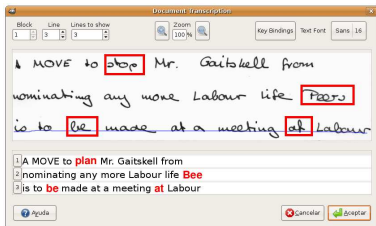
Feature Selection

- Hassan Chouaib, PhD candidate, S. Tabbone (LORIA) and Prof. N. Vincent (Paris 5)
- Combine Genetic Algorithms (GA) and boosting-based classifiers.
- Use of R-Signature, Zernike moments and pixel images as shape descriptors.

GiDoc



GiDoc



- Offers an interactive environment
- Usefull for groundtruthing
- based on gimp
- HMM are estimated by the means of HTK engine
- Language models estimated by SRILM

The End

Before concluding...

Any question?